

ON THE COMPLETENESS OF NON-SYMMETRICAL UNIFORM CONVERGENCE WITH SOME LINKS TO APPROACH SPACES

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Abstract. The quasitopos **b-UFIL** of b-uniform filter spaces [16] are an appropriate tool for studying convergence from a higher point of view as demonstrated in recent papers by the above mentioned authors. In addition BORN, the category of bornological spaces and bounded maps, can be integrated as bicoreflective subcategory of **b-UFIL**. As already shown symmetric b-uniform filter spaces have “Cauchy completions” which generalize some important ones as for example those which were considered by Wyler, Preuss, Czászár and Hausdorff, respectively. In the present paper we will construct a completion, called ultracompletion, for a suitable not necessarily symmetric b-uniform filter space and compare this one with a construct presented for quasi-uniform spaces by Carlson and Hicks in the past. Furthermore, among others, we get the result that every quasiuniform limit space in the sense of Behling has an ultracompletion. At the end of this article, we consider some important links to generalized approach spaces, those which were introduced by Lowen. So it is shown that b-topological closure operators can be completely described by so-called approach-bornologies, which represent a common generalization of both approach spaces and bornological spaces, respectively. Thus, as interesting corollary we obtain the result that **APB** the category of approach-bornological spaces and contracted maps intersects **b-URING**, the full subcategory of **b-UFIL**, whose objects have ultracompletions.

1. INTRODUCTION

In our last paper “The Cauchy-completion of a symmetric b-uniform filter space” we announce the question whether there exist completions for given not necessarily symmetric b-uniform filter spaces. Here, a b-uniform filter space is a triple consisting of a non-empty subset $\mathcal{B}^X \subset \underline{P}X$ and a non-empty subset

$$\mu \subset \text{FIL}(X \times X) := \{\mathcal{U} : \mathcal{U} \text{ is filter on } X \times X\}$$

such that the following conditions hold

- (buf₁) $B_1 \subset B \in \mathcal{B}^X$ implies $B_1 \in \mathcal{B}^X$;
- (buf₂) $x \in X$ implies $\{x\} \in \mathcal{B}^X$;
- (buf₃) $B \in \mathcal{B}^X \setminus \{\emptyset\}$ implies $\dot{B} \times \dot{B} \in \mu$, where $\dot{B} := \{A \subset X : A \supset B\}$;
- (buf₄) $\mathcal{U} \in \mu$ and $\mathcal{U} \subset \mathcal{U}_1 \in \text{FIL}(X \times X)$ imply $\mathcal{U}_1 \in \mu$.

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In general, for filters \mathcal{F} and \mathcal{G} , their *cross product* is defined by $\mathcal{F} \times \mathcal{G} := \{R \subset X \times X : \exists F \in \mathcal{F} \exists G \in \mathcal{G} \text{ s.t. } R \supset F \times G\}$.

For b-uniform filter spaces $(X, \mathcal{B}^X, \mu_X)$, $(Y, \mathcal{B}^Y, \mu_Y)$ a function $f : X \rightarrow Y$ is called *b-uniformly continuous* map, provided that the following conditions are satisfied,

- (buc₁) $B \in \mathcal{B}^X$ implies $f[B] \in \mathcal{B}^Y$;
- (buc₂) $\mathcal{U} \in \mu_X$ implies $(f \times f)(\mathcal{U}) \in \mu_Y$.

By **b-UFIL** we denote the category of b-uniform filter spaces and b-uniformly continuous maps.

In this context we point out that \mathcal{B}^X defines a $\underline{\mathbb{B}}$ -set in the sense of Wyler [25]. On the other hand if \mathcal{B}^X is discrete, meaning that $\mathcal{B}^X = \mathcal{D}^X := \{\emptyset\} \cup \{\{x\} : x \in X\}$ holds, then b-uniform filter spaces and preuniform convergence spaces in the sense of Preuss [22] are essentially the same (up to isomorphism); meaning that **DISb-UFIL** the full subcategory of **b-UFIL**, whose objects are discrete is isomorphic to **PUCONV**, the category of preuniform convergence spaces and uniformly continuous maps.

Furthermore the quasi-topos **BOUND** of bound spaces and bounded maps [23] can also be fully embedded into **b-UFIL**.

Here, a bound space is a pair (X, \mathcal{B}^X) , where \mathcal{B}^X denotes a $\underline{\mathbb{B}}$ -set, and the morphisms between them are the bounded maps, compare with (buc₁). Then, for an arbitrary $\underline{\mathbb{B}}$ -set \mathcal{B}^X we consider the pair (\mathcal{B}^X, μ_b) , where μ_b is defined by setting

$$\mu_b := \{\mathcal{U} \in \text{FIL}(X \times X) : \exists B \in \mathcal{B}^X \text{ s.t. } \overset{\bullet}{B} \times \overset{\bullet}{B} \subset \mathcal{U}\}.$$

Conversely, for a *bounded* b-uniform filter space (X, \mathcal{B}^X, η) , meaning that (\mathcal{B}^X, η) is satisfying the following condition,

- (B) $\mathcal{V} \in \eta$ implies the existence of an $B \in \mathcal{B}^X$ with $B \times B \in \mathcal{V}$,

the so defined assignments deliver an isomorphism between the category **BOUND** and **B-UFIL**, the full subcategory of **b-UFIL** whose objects are bounded. Furthermore **B-UFIL** is bicoreflective in **b-UFIL**. In fact let (X, \mathcal{B}^X, μ) be a b-uniform filter space, then by setting $\mu^B := \{\mathcal{U} \in \mu : \exists B \in \mathcal{B}^X B \times B \in \mathcal{U}\}$ we obtain a bounded b-uniform filter space such that $1_X : (X, \mathcal{B}^X, \mu^B) \rightarrow (X, \mathcal{B}^X, \mu)$ is the bicoreflection of (X, \mathcal{B}^X, μ) with respect to **B-UFIL**. Now, in addition let us call a b-uniform filter space (X, \mathcal{B}^X, μ) *bornological* provided that \mathcal{B}^X forms a bornology, meaning that \mathcal{B}^X in addition satisfies $B_1, B_2 \in \mathcal{B}^X$ imply $B_1 \cup B_2 \in \mathcal{B}^X$. By **BONb-UFIL** we denote the full subcategory of **b-UFIL**, whose objects are bornological. Then, the category **BORN** of bornological spaces and bounded maps, [9] can be regarded as full subcategory of the intersection of **BONb-UFIL** and **B-UFIL**, respectively. Finally we still mention the concept of final b-uniform filter spaces, regarded as full subcategory of **b-UFIL**, denoted by **FINb-UFIL** and whose objects are *final*, meaning that the corresponding $\underline{\mathbb{B}}$ -sets are satisfying the following condition,

- (f) $B \in \mathcal{B}^X$ implies B is finite.

Here we note that every finite b-uniform filter space is final, and furthermore we state that each discrete b-uniform filter space is final, too.

Thus final b -uniform filter spaces represent roughly spoken a common generalization of uniform convergence and the bornologies of finite sets. Later (see up to 5.11) we will see which important role they are playing in the context of ultracompleteness.

Finally, we infer that **FINb-UFIL** is bicoreflective in **b-UFIL**. To these facts, we note that in our view filters may contain the empty set. This is of importance, too, if one considers set-convergence spaces in the sense of Wyler [25].

A set-convergence is a pair (\mathcal{B}^X, q) , where \mathcal{B}^X is \underline{B} -set and $q \subset \mathcal{B}^X \times \text{FIL}(X)$, such that the following conditions are satisfied,

- (SC₁) $B \in \mathcal{B}^X$ implies $(B, \overset{\bullet}{B}) \in q$;
- (SC₂) $(\emptyset, \mathcal{F}) \in q$ implies $\mathcal{F} = \underline{P}X$;
- (SC₃) $(B, \mathcal{F}) \in q$ and $\mathcal{F} \subset \mathcal{F}_1 \in \text{FIL}(X)$ imply $(B, \mathcal{F}_1) \in q$.

Then, the triple (X, \mathcal{B}^X, q) is called a *set-convergence space*. Often we write $\mathcal{F} q B$ iff $(B, \mathcal{F}) \in q$ is valid.

A function $f : X \rightarrow Y$ between set-convergence spaces $(X, \mathcal{B}^X, q_X), (Y, \mathcal{B}^Y, q_Y)$ is called *b-continuous* provided that f is bounded, and in addition, f transfers convergent filters. By **SETCONV** we are denoting the corresponding category. An important subcategory of **SETCONV** is the bireflective full subcategory **RO-SETCONV**, whose objects are reordered. Here, a set-convergence (\mathcal{B}^X, q) is called reordered, and the triple (X, \mathcal{B}^X, q) a *reordered set-convergence space*, provided it satisfies the following conditions,

- (RO) $\emptyset \neq B_1 \subset B \in \mathcal{B}^X$ and $\mathcal{F} q B$ imply $\mathcal{F} q B_1$.

Here, we should mention that now classical point-convergence spaces, such as KENT-convergence spaces, limit spaces, pseudo-topological spaces, pre-topological spaces or topological spaces as well can be regarded as special reordered set-convergence spaces by restricting \mathcal{B}^X to \mathcal{D}^X [6] (see Section 3).

Note also that **RO-SETCONV** can be fully embedded into **b-UFIL** as follows: For reordered set-convergence space (X, \mathcal{B}^X, q) we consider the triple $(X, \mathcal{B}^X, \mu_q)$, where μ_q is defined by setting:

$$\mu_q := \{ \mathcal{U} \in \text{FIL}(X \times X) : \exists \mathcal{F} \in \text{FIL}(X) \exists B \in \mathcal{B}^X \setminus \{ \emptyset \} \\ (\mathcal{F} q B \text{ and } \overset{\bullet}{B} \times \mathcal{F} \subset \mathcal{U}) \} \cup \{ \underline{P}(X \times X) \}.$$

Then, (\mathcal{B}^X, μ_q) forms a so-called *b-uniform convergence*, and the triple $(X, \mathcal{B}^X, \mu_q)$ a *b-uniform convergence space*.

Here, a b -uniform filter space (X, \mathcal{B}^X, η) is called *b-uniform convergence space*, provided that (\mathcal{B}^X, η) satisfies the following condition,

- (cv) $\mathcal{U} \in \eta$ implies the existence of $\mathcal{F} \in \text{FIL}(X)$ and $B \in \mathcal{B}^X$ with $\mathcal{U} \supset \overset{\bullet}{B} \times \mathcal{F} \in \eta$.

In this context $\mathcal{F} p_\eta B$ is defined by setting:

$$\mathcal{F} p_\eta \emptyset \quad \text{iff} \quad \mathcal{F} = \underline{P}X \text{ and} \\ \mathcal{F} p_\eta B \quad \text{iff} \quad \overset{\bullet}{B} \times \mathcal{F} \in \eta \text{ for every } B \in \mathcal{B}^X \setminus \{ \emptyset \}.$$

The so-defined assignments deliver an isomorphism between the categories

$$\mathbf{RO-SETCONV} \quad \text{and} \quad \mathbf{b-UCONV},$$

whose objects are the b-uniform convergence spaces. Thus our new developed concept seems to be an appropriate tool for a *common study* of all former investigated categories.

In giving some *intrinsic* examples let us consider a quasi-uniform space (X, \mathcal{U}) , [12] and let $\mathcal{U}^{-1} := \{U^{-1} : U \in \mathcal{U}\}$ be the *conjugate* quasi-uniformity, where $U^{-1} := \{(y, x) : (x, y) \in U\}$. If \mathcal{S} is a non-empty family of subsets of X , we may consider the following three convergences on $\underline{P}X$. Let (A_t) be a net of subsets of X and $A \subset X$. We say that the net (A_t) :

\mathcal{S}^- -converges to A , and we write $A_t \xrightarrow{\mathcal{S}^-} A$ provided for each $S \in \mathcal{S}$ and $U \in \mathcal{U}$ there exists t_0 such that $A \cap S \subset U^{-1}(A_t)$ for every $t \geq t_0$;

\mathcal{S}^+ -converges to A , and we write $A_t \xrightarrow{\mathcal{S}^+} A$, provided for each $S \in \mathcal{S}$ and $U \in \mathcal{U}$ there exists t_0 such that $A_t \cap S \subset U(A)$ for every $t \geq t_0$;

$\widehat{\mathcal{S}}$ -converges to A provided it \mathcal{S}^- -converges to A and it \mathcal{S}^+ -converges to A , where $U(A) := \{y \in X : (x, y) \in U \text{ for some } x \in A\}$, $U^{-1}(A) := \{y \in X : (x, y) \in U^{-1} \text{ for some } x \in A\}$.

Note that if X is a metric space and $\mathcal{S} = \{X\}$ then the $\widehat{\mathcal{S}}$ -converges on the space of closed bounded subsets of X is simply the H -convergence, i.e. the convergence in the Hausdorff metric. The just presented ideas are going back to A. Lechicki, S. Levi and A. Spakowski [13] where in their work Bornological converges one also can find additional examples and corresponding references, see also [24].

Now, to tackle our problem we have to alter the definition of a μ -Cauchy filter [17] so that, in the symmetric case, they coincide.

2. BASIC NOTIONS

Definition 2.1. Let (X, \mathcal{B}^X, μ) be a b-uniform filter space, $\mathcal{C} \in \text{FIL}(X) \setminus \{\underline{P}X\}$ is called *pre-Cauchy filter* (shortly *pre-Chy filter*) in (\mathcal{B}^X, μ) , provided \mathcal{C} satisfies the following condition,

(pChy) $\exists \mathcal{U} \in \mu$ s.t. $\forall R \in \mathcal{U} \exists B \in \mathcal{B}^X \setminus \{\emptyset\}$ s.t. $R(B) \in \mathcal{C}$.

Here $R(B) := \{z \in X : \exists x \in B \text{ s.t. } (x, z) \in R\}$.

Remark 2.2. Here we should note that in the discrete case for a symmetric b-uniform net space (X, \mathcal{B}^X, μ) and a filter $\mathcal{C} \in \text{FIL}(X) \setminus \{\underline{P}X\}$ the following statements are equivalent:

- (i) \mathcal{C} is pre-Chy filter in (\mathcal{B}^X, μ) ;
- (ii) \mathcal{C} is μ -Chy filter [17].

Here, $\mathcal{C} \in \text{FIL}(X) \setminus \{\underline{P}X\}$ is called *μ -Chy filter* iff $\mathcal{C} \times \mathcal{C} \in \mu$ is valid. Thus, if returning to the discrete case \mathcal{C} defines a Cauchy-filter as usual on the associated uniform limit space, [22]. Moreover, we note that roughly spoken the b-uniformly continuous image of a pre-Chy filter is a pre-Chy filter again.

Definition 2.3. Let (X, \mathcal{B}^X, μ) be a b-uniform filter space. Then, $\mathcal{F} \in \text{FIL}(X)$ is called *setconvergent* in (\mathcal{B}^X, μ) iff there exists $B \in \mathcal{B}^X \setminus \{\emptyset\}$ s.t. $\dot{B} \times \mathcal{F} \in \mu$.

Remark 2.4. By the definition used in Introduction, this can be expressed by the fact that $\mathcal{F} p_\mu B$ is valid for some $B \in \mathcal{B}^X \setminus \{\emptyset\}$.

Now it is clear that every setconvergent filter $\mathcal{F} \in FIL(X) \setminus \{\underline{P}X\}$ in (\mathcal{B}^X, μ) is a pre-Chy filter. In this context we also note that for an reordered set-convergence space (X, \mathcal{B}^X, q) and a filter $\mathcal{F} \in FIL(X)$ the following statements are equivalent:

- (i) $\mathcal{F} q B$ for some $B \in \mathcal{B}^X \setminus \{\emptyset\}$;
- (ii) $\mathcal{F} q \{x\}$ for some $x \in X$.

Definition 2.5. A b-uniform filter space (X, \mathcal{B}^X, μ) is called *ultracomplete*, provided that every pre-Chy filter in (\mathcal{B}^X, μ) is setconvergent.

Example 2.6. Every non-empty bornological bounded b-uniform filter space (X, \mathcal{B}^X, μ) is ultracomplete.

Proof. Let $\mathcal{C} \in FIL(X) \setminus \{\underline{P}X\}$ be a pre-Chy filter in (\mathcal{B}^X, μ) , hence we can find $\mathcal{U} \in \mu$ with the corresponding property. But by the hypothesis (\mathcal{B}^X, μ) is bounded, thus $B \times B \in \mathcal{U}$ for some $B \in \mathcal{B}^X$. Then, we can choose $D \in \mathcal{B}^X \setminus \{\emptyset\}$ s.t. $(B \times B)(D) \in \mathcal{C}$ by applying the pre-Cauchy property, hence $D \cup B \in \mathcal{B}^X \setminus \{\emptyset\}$, since \mathcal{B}^X is bornology. Consequently, $(D \overset{\bullet}{\cup} B) \times (D \overset{\bullet}{\cup} B) \in \mu$ follows. It remains to prove $(D \overset{\bullet}{\cup} B) \subset \mathcal{C}$, because then $\mathcal{C} q_\mu D \cup B$ is valid.

$A \in (D \overset{\bullet}{\cup} B)$ implies $A \supset D \cup B$. We will show that the inclusion $D \cup B \subset (B \times B)(D)$ holds. $z \in (B \times B)(D)$ implies the existence of $x \in D$ such that $(x, z) \in B \times B$, and $z \in D \cup B$ follows, proving the claim. \square

Example 2.7. Every non-empty b-uniform convergence space (X, \mathcal{B}^X, μ) is ultracomplete.

Proof. Let $\mathcal{C} \in FIL(X) \setminus \{\underline{P}X\}$ be a pre-Chy filter in (\mathcal{B}^X, μ) , hence we can find an $\mathcal{U} \in \mu$ with the corresponding property. Since (X, \mathcal{B}^X, μ) is b-uniform convergence space, there exists $B \in \mathcal{B}^X$ and a filter $\mathcal{F} \in FIL(X)$ such that $\mathcal{U} \supset \overset{\bullet}{B} \times \mathcal{F} \in \mu$ are valid. B is not empty and \mathcal{F} is subfilter of \mathcal{C} and thus $\mathcal{F} \neq \underline{P}X$. Because $F \in \mathcal{F}$ implies $B \times F \in \mathcal{U}$, hence we can find $D \in \mathcal{B}^X \setminus \{\emptyset\}$ with $(B \times F)(D) \in \mathcal{C}$. Since $(B \times F)(D) \subset F$ holds, $F \in \mathcal{C}$ follows, and consequently $\overset{\bullet}{B} \times \mathcal{C} \in \mu$ results, which shows $\mathcal{C} q_\mu B$. \square

Now, we introduce two further important notions which are closed to the former presented concept.

Definition 2.8. A b-uniform filter space (X, \mathcal{B}^X, μ) is called

- (i) *ultracompact* provided that each ultrafilter $\mathcal{F} \in FIL(X) \setminus \{\underline{P}X\}$ is setconvergent in (\mathcal{B}^X, μ) ;
- (ii) *ultrabounded* provided that each ultrafilter $\mathcal{F} \in FIL(X) \setminus \{\underline{P}X\}$ is a pre-Chy filter in (\mathcal{B}^X, μ) .

Remark 2.9. Evidently, each non-empty finite b-uniform filter space is ultracompact. Moreover, every ultracompact b-uniform filter space is ultrabounded, and in addition we get that every ultrabounded and ultracomplete b-uniform filter space is ultracompact again.

Furthermore we note that, supposing a symmetric b-uniform net space (X, \mathcal{B}^X, μ) , then $\mathcal{F} \in FIL(X)$ is setconvergent in (\mathcal{B}^X, μ) iff $\mathcal{F} q_{\tau_\mu} B$ is valid for some $B \in \mathcal{B}^X \setminus \{\emptyset\}$.

Here $\mathcal{F} q_{\tau_\mu} B$ iff $\mathcal{F} \cap \overset{\bullet}{B} \in \tau_\mu$ [15]. Thus we get that for a symmetric b-uniform net space the terms compactness and ultracompactness are essentially the same. Then, finally, if considering the discrete case we obtain the fundamental result that a symmetric b-uniform net space is ultracompact iff it is ultrabounded and ultracomplete. Now taking all these facts into account we resume that the new terms introduced generalize the older ones of compactness, precompactness and completeness, respectively in a rather natural way.

3. MORE ABOUT SET-CONVERGENCE

Returning to the concept of reordered set-convergence we should explain how it plays an important role for further studies of point-convergences, not only restricted to the discrete case.

Now, if one considers point-convergence on arbitrary \underline{B} -sets, such as the set \mathcal{E}^X of all finite subsets or the set τ^X of all totally bounded subsets or the set \mathcal{C}^X of all compact subsets of a set X we extend the basics to the following one, i.e.

Definition 3.1. We call a reordered set-convergence (\mathcal{B}^X, q) *pointset-convergence* (on X), and the triple (X, \mathcal{B}^X, q) *pointset-convergence space*, provided that the following condition is satisfied, i.e.

$$(\text{pset}) \mathcal{F} \in \text{FIL}(X), B \in \mathcal{B}^X \setminus \{\emptyset\} \text{ and } \mathcal{F} q \{x\} \forall x \in B \text{ imply } \mathcal{F} q B.$$

Remark 3.2. Here we point out, that each discrete set-convergence space is a pointset-convergence space. Convergence in the usual sense like limit spaces or pretopological spaces, respectively are being involved [6]. Consequently, all possible point-convergences on any \underline{B} -sets can be now subsumed under the concept of pointset-convergence spaces. If we denote by **P-SETCONV** the corresponding full subcategory of **RO-SETCONV**, then we claim that **P-SETCONV** is bireflective in **RO-SETCONV**.

In fact for a reordered set-convergence space (X, \mathcal{B}^X, q) we put for $\mathcal{F} \in \text{FIL}(X)$ and $B \in \mathcal{B}^X \setminus \{\emptyset\}$ $\mathcal{F} \overset{\bullet}{q} B$ iff $\mathcal{F} q \{x\} \forall x \in B$, and $\mathcal{F} \overset{\bullet}{q} \emptyset$ iff $\mathcal{F} = \underline{P}X$. Then, $(X, \mathcal{B}^X, \overset{\bullet}{q})$ is a pointset-convergence space such that the demand for the bireflection is satisfied.

Another point of view is considering the set-convergence (\mathcal{B}^X, q_μ) being induced by a given generated b-uniform filter space (X, \mathcal{B}^X, μ) . As already seen [17, 22] generated b-uniform filter spaces are in one-to-one correspondence with principal preuniform convergence spaces or preuniform spaces or diagonal filters in the sense of Weil [1] by assuming the discrete case. So we are coming quite naturally to the following definition:

Definition 3.3. A set-convergence (\mathcal{B}^X, q) is called *set-surrounding* and the triple (X, \mathcal{B}^X, q) *set-surrounding space*, provided that the following property is valid,

$$(\text{ss}) B \in \mathcal{B}^X \setminus \{\emptyset\} \text{ implies } \bigcap \{\mathcal{F} : \mathcal{F} q B\} q B.$$

Remark 3.4. Let a neighborhood space $(X, \mathcal{B}^X, \Theta)$ be given [23], then the triple $(X, \mathcal{B}^X, q_\Theta)$ defines a set-surrounding space, where

$$\mathcal{F} q_\Theta B \text{ iff } \mathcal{F} \supset \Theta(B) \forall B \in \mathcal{B}^X.$$

Lemma 3.5. *If (X, \mathcal{B}^X, μ) is a generated b-uniform filter space, then the underlying set convergence (\mathcal{B}^X, q_μ) is a set-surrounding on X and determines the set-surrounding space $(X, \mathcal{B}^X, q_\mu)$.*

Proof. Let $B \in \mathcal{B}^X \setminus \{\emptyset\}$ and consider all $\mathcal{F} \in \text{FIL}(X)$ s.t. $\mathcal{F} q_\mu B$ is valid, hence $\overset{\bullet}{B} \times \mathcal{F} \in \mu$ holds for those $\mathcal{F} \in \text{FIL}(X)$. It remains to show that the statement $\overset{\bullet}{B} \times \cap \{\mathcal{F} \in \text{FIL}(X) : \mathcal{F} q_\mu B\} \in \mu$ can be deduced. Therefore, it suffices to show that the inclusion $\cap \mu \subset \overset{\bullet}{B} \times \cap \{\mathcal{F} \in \text{FIL}(X) : \mathcal{F} q_\mu B\}$ holds, since by the hypothesis μ is generated. So let $R \in \mu$, hence $R \supset B \times F_{\mathcal{F}}$ for some $F_{\mathcal{F}} \in \mathcal{F}$ with $\mathcal{F} q_\mu B$. Consequently, $R \supset \cup \{B \times F_{\mathcal{F}} : \mathcal{F} q_\mu B\} \supset B \times \cup \{F_{\mathcal{F}} : \mathcal{F} q_\mu B\}$, because $(x, z) \in B \times \cup \{f_{\mathcal{F}} : \mathcal{F} q_\mu B\}$ implies $x \in B$, and there exists $\mathcal{F}' \in \text{FIL}(X)$ with $\mathcal{F}' q_\mu B$ and $z \in F'_{\mathcal{F}}$. Consequently, $(x, z) \in B \times F_{\mathcal{F}'}$ implies $(x, z) \in \cup \{B \times F_{\mathcal{F}} : \mathcal{F} q_\mu B\}$. But $B \times \cup \{F_{\mathcal{F}} : \mathcal{F} q_\mu B\} \in \overset{\bullet}{B} \times \cap \{\mathcal{F} \in \text{FIL}(X) : \mathcal{F} q_\mu B\}$, and the claim follows. \square

Remark 3.6. Here we point out, that in the discrete case $(X, \mathcal{B}^X, q_\mu)$ even defines a pretopological space. Then, a related expression aims at so-called closure operators. Indeed, let a b-uniform filter space (X, \mathcal{B}^X, μ) be given, then we can define the following two closure spaces (X, cl_μ) and (X, cl^μ) by setting:

$$cl_\mu(\emptyset) := \emptyset \quad \text{and}$$

$$cl_\mu(A) := \{x \in X : \exists \mathcal{F} \in \text{FIL}(X) (\overset{\bullet}{x} \times \mathcal{F} \in \mu \text{ and } A \in \text{sec}\mathcal{F})\} \quad \forall (\emptyset \neq A) \in \underline{PX},$$

where $\text{sec}\mathcal{F} := \{D \subset X : \forall F \in \mathcal{F} F \cap D \neq \emptyset\}$.

Respectively, we put:

$$cl^\mu(\emptyset) := \emptyset \quad \text{and}$$

$$cl^\mu(A) := \{x \in X : \exists \mathcal{U} \in \mu \text{ s.t. } \{x\} \times A \in \text{sec}\mathcal{U}\}, \quad \forall (\emptyset \neq A) \in \underline{PX}$$

Here, in general we note that $cl_\mu(A) \subset cl^\mu(A)$ is true for every $A \in \underline{PX}$. In the case of (X, \mathcal{B}^X, μ) being b-uniform convergence space then the equality of both the closures results. The latter closure defined will be used in 5.1 in obtaining that X is dense in X^* .

4. B-UNIFORM RING SPACES

Before coming to the core of this article, we introduce the following important notion.

Definition 4.1. For a b-uniform filter space (X, \mathcal{B}^X, μ) a pair (\mathcal{A}^X, η) with $\emptyset \neq \mathcal{A}^X \subset \underline{PX}$ and $\emptyset \neq \eta \in \text{FIL}(X \times X)$ is called a base for (\mathcal{B}^X, μ) , provided that the following equations hold,

$$(\text{bas}_1) \quad \mathcal{B}^X = \{B \subset X : \exists A \in \mathcal{A}^X \text{ s.t. } B \subset A\} \quad \text{and}$$

$$(\text{bas}_2) \quad \mu = \{\mathcal{V} \in \text{FIL}(X \times X) : \exists \mathcal{U} \in \eta \text{ s.t. } \mathcal{U} \subset \mathcal{V}\} \quad (\text{compare with [1]}).$$

Remark 4.2. Here we should note that a pair (\mathcal{A}^X, η) is a base for a b-uniform filter structure on X iff it satisfies the following conditions:

$$(\text{bsuf}_1) \quad \emptyset \in \mathcal{A}^X;$$

$$(\text{bsuf}_2) \quad x \in X \text{ implies } \{x\} \in \mathcal{A}^X;$$

(bsuf₃) $\forall B \in \mathcal{B}^X \setminus \{\emptyset\} \exists \mathcal{U} \in \eta$ s.t. $\mathcal{U} \subset \overset{\bullet}{B} \times \overset{\bullet}{B}$.

Lemma 4.3. *For b-uniform filter spaces $(X, \mathcal{B}^X, \mu_X)$, $(Y, \mathcal{B}^Y, \mu_Y)$ let $f : X \rightarrow Y$ be a map. Let us denote by (\mathcal{A}^X, η_X) respectively (\mathcal{A}^Y, η_Y) bases for the corresponding spaces. Then, the following statements are equivalent:*

- (i) $f : (X, \mathcal{B}^X, \mu_X) \rightarrow (Y, \mathcal{B}^Y, \mu_Y)$ is b-uniformly continuous;
- (ii) (1) $A \in \mathcal{A}^X$ implies $\exists A^Y \in \mathcal{A}^Y$ s.t. $f[A] \subset A^Y$;
 (2) $\mathcal{U} \in \mu_X$ implies $\exists \mathcal{U}_Y \in \eta_Y$ s.t. $\mathcal{U}_Y \subset (f \times f)(\mathcal{U})$.

Proof. By straightforward executing. □

As pointed out by many authors in the past, quasi-uniform spaces, quasiuniform convergence spaces, Cauchy spaces or point-convergence spaces, respectively are also of interest if one considers suitable extensions of the given constructs [4, 5, 7, 8, 11, 14].

Here we note again that all the above mentioned spaces can be simply described by the associated b-uniform filter spaces. Moreover each of them fulfills an additional common property, which we will be now described as follows:

Definition 4.4. A b-uniform filter structure (\mathcal{B}^X, μ) is called *b-uniform ring structure* (on X) and the space (X, \mathcal{B}^X, μ) *b-uniform ring space*, provided it satisfies the following condition, i.e.

- (rg) $\mathcal{U} \in \mu$ implies $\mathcal{U} \circ \mathcal{U} \in \mu$, where in general for filters $\mathcal{U}, \mathcal{V} \in \text{FIL}(X \times X)$, $\mathcal{U} \circ \mathcal{V} := \{R \subset X \times X : \exists U \in \mathcal{U} \exists V \in \mathcal{V} \text{ s.t. } R \supset U \circ V\}$.

- Examples 4.5.**
- (i) Let (X, \mathcal{U}) be a quasi-uniform space. Then, the associated space $(X, \mathcal{D}^X, \mu_{\mathcal{U}})$ defines a b-uniform ring space, where $\mu_{\mathcal{U}} := \{\mathcal{V} \in \text{FIL}(X \times X) : \mathcal{V} \supset \mathcal{U}\}$. Note, that the pair $(\mathcal{D}^X, \{\mathcal{U}\})$ defines a base for $(\mathcal{D}^X, \mu_{\mathcal{U}})$;
 - (ii) Let (X, J_X) be a quasiuniform convergence space. Then, the associated space (X, \mathcal{D}^X, J_X) defines a b-uniform ring space;
 - (iii) for a b-filter space $(X, \mathcal{B}^X, \Gamma)$ [11, 15, 17] the space $(X, \mathcal{B}^X, \mu_{\Gamma})$ defines a b-uniform ring space, where the pair $(\mathcal{B}^X, \{\mathcal{F} \times \mathcal{F} : \mathcal{F} \in \Gamma\})$ forms a base for $(\mathcal{B}^X, \mu_{\Gamma})$;
 - (iv) Every b-uniform net space is a b-uniform ring space [17];
 - (v) Every bounded b-uniform filter space (X, \mathcal{B}^X, μ) is a b-uniform ring space, where $(\mathcal{B}^X, \{B \times B : B \in \mathcal{B}^X\})$ forms a base for (\mathcal{B}^X, μ) ;
 - (vi) For a reordered set-convergence space (X, \mathcal{B}^X, q) the space $(X, \mathcal{B}^X, \mu_q)$ defines a b-uniform ring space, where the pair $(\mathcal{B}^X, \{\overset{\bullet}{B} \times \mathcal{F} : \mathcal{F} q B, B \in \mathcal{B}^X\})$ forms a base for (\mathcal{B}^X, μ_q) ;
 - (vii) For a neighbourhood space $(X, \mathcal{B}^X, \Theta)$, [23] the space $(X, \mathcal{B}^X, \mu_{\Theta})$ defines a b-uniform ring space, where $(\mathcal{B}^X, \{\overset{\bullet}{B} \times \Theta(B) : B \in \mathcal{B}^X\})$ forms a base for $(\mathcal{B}^X, \mu_{\Theta})$.

Proposition 4.6. *A pair (\mathcal{A}^X, η) is a base for a b-uniform ring structure iff it satisfies the conditions in 4.2. and in addition the following one, i.e.*

- (rbas) $\mathcal{U} \in \eta$ implies the existence of $\mathcal{V} \in \eta$ s.t. $\mathcal{V} \subset \mathcal{U} \circ \mathcal{U}$.

Remark 4.7. Here we again assume that all mentioned bases in 4.5 even define the condition (rbas). So let us call a pair (\mathcal{A}^X, η) satisfying these conditions a *ring base*. Now in applying this new definition we characterize pre-Chy filters in a b-uniform ring space (X, \mathcal{B}^X, μ) by a given ring base (\mathcal{A}^X, η) as follows:

$\mathcal{C} \in \text{FIL}(X)$ is a pre-Chy filter in (\mathcal{B}^X, μ) iff $\exists \mathcal{U} \in \eta \forall R \in \mathcal{U} \exists A \in \mathcal{A}^X$ s.t. $R(A) \in \mathcal{C}$.

In 4.5(iv) we pointed out that b-uniform net spaces are in fact b-uniform ring spaces. Now, for generated b-uniform filter spaces the following statements are equivalent:

- (i) (X, \mathcal{B}^X, μ) is a b-uniform net space;
- (ii) (X, \mathcal{B}^X, μ) is a b-uniform ring space.

Proof. Evident. □

Remark 4.8. In this context we also mention that for a generated b-uniform filter space (X, \mathcal{B}^X, μ) , (X, \mathcal{B}^X, μ) is a b-uniform net space iff $(X, \mathcal{B}^X, \cap\mu)$ defines a quasi-uniform space, provided that \mathcal{B}^X is discrete with $\cap\mu := \cap\{\mathcal{U} : \mathcal{U} \in \mu\}$.

Note that (X, \mathcal{U}) is a quasi-uniform space iff the principal preuniform convergence space $(X, [\mathcal{U}])$ defines a quasiuniform convergence space [1]. At the end of this section we add the fact that each b-uniform filter space (X, \mathcal{B}^X, μ) induces a b-uniform ring space $(X, \mathcal{B}^X, \overset{\circ}{\mu})$ by defining a ring base $(\mathcal{B}^X, \overset{\circ}{b})$ with $\overset{\circ}{b} := \{\mathcal{U} \in \mu : \mathcal{U} \subset \mathcal{U} \circ \mathcal{U}\}$. The identity map $1_X : (X, \mathcal{B}^X, \overset{\circ}{\mu}) \rightarrow (X, \mathcal{B}^X, \mu)$ is b-uniform continuous by applying 4.3, and moreover if $(Y, \mathcal{B}^Y, \mu_Y)$ is b-uniform ring space and $f : (Y, \mathcal{B}^Y, \mu_Y) \rightarrow (X, \mathcal{B}^X, \mu)$ an injective b-uniformly continuous map, then $f : (Y, \mathcal{B}^Y, \mu_Y) \rightarrow (X, \mathcal{B}^X, \overset{\circ}{\mu})$ is b-uniformly continuous, too.

Thus, each b-uniform filter space (X, \mathcal{B}^X, μ) has a restricted co-universal map with respect to the inclusion functor $F : \mathbf{b-URING} \rightarrow \mathbf{b-UFIL}$, where $\mathbf{b-URING}$ denotes the full subcategory of $\mathbf{b-UFIL}$, whose objects are the b-uniform ring spaces.

Theorem 4.9. $\mathbf{b-URING}$ forms a topological construct [22].

Proof. For any set X , the class $\{(Y, \mathcal{B}^Y, \mu) \in |\mathbf{b-URING}| : X = Y\}$ of all $\mathbf{b-URING}$ objects with underlying set X is a set, because of $(\mathcal{B}^Y, \mu) \in \underline{P}(\underline{P}X) \times \underline{P}(\text{FIL}(X \times X))$.

The only b-uniform ring structure on a set X with $\text{Card}X = 1$ is the pair $(\{\emptyset, \{x\}, \{\overset{\bullet}{x} \times \overset{\bullet}{x}, \underline{P}(\{x\} \times \{x\})\})$, where x denotes the element of X . If X is empty, then $(\{\emptyset\}, \{\{\emptyset\}\})$ represents the only b-uniform ring structure on X .

For a set X , let I be a class, $(X_i, \mathcal{B}^{X_i}, \mu_i)_{i \in I}$ a family of b-uniform ring spaces and $(f_i : X \rightarrow X_i)_{i \in I}$ a family of maps. Then, $(\mathcal{B}_I^X, \mu_X^I)$ is the initial $\mathbf{b-URING}$ structure on X , where

$$\begin{aligned} \mathcal{B}_I^X &:= \{B \subset X : \forall i \in I f_i[B] \in \mathcal{B}^{X_i}\} \text{ and} \\ \mu_X^I &:= \{\mathcal{U} \in \text{FIL}(X \times X) : \forall i \in I (f_i \times f_i)(\mathcal{U}) \in \mu_i\}. \end{aligned}$$

Then, the remaining is clear. □

Remark 4.10. The initial b-uniform ring structure on a set X with respect to $(X, f_i, (X_i, \mathcal{B}^{X_i}, \mu_i), I)$ is the coarsest b-uniform ring structure on X such that f_i is b-uniformly continuous for each $i \in I$.

Specifically, let (X, \mathcal{B}^X, μ) be a b-uniform ring space and $A \subset X$. Then, (\mathcal{B}^A, μ_A) is b-uniform ring structure on A , where

$$\begin{aligned} \mathcal{B}^A &:= \{B \cap A : B \in \mathcal{B}^X\} \text{ and} \\ \mu_A &:= \{\mathcal{U}_A : \mathcal{U} \in \mu\} \text{ with } \mathcal{U}_A := \{R \cap (A \times A) : R \in \mathcal{U}\}, \end{aligned}$$

such that $(A, \mathcal{B}^A, \mu_A)$ represents the b-uniform ring subspace of (X, \mathcal{B}^X, μ) in **b-URING**.

5. THE ULTRACOMPLETION OF A B-UNIFORM RING SPACE

Now, in answering the main question of this paper, we will construct an ultracompletion for an arbitrary non-empty b-uniform ring space and then apply this result to some former treated special constructs. In addition we study certain separation properties especially those the space may possess to carry over to the ultracompletion. Here, we extend an idea for quasi-uniform spaces due to Carlson and Hicks [3] as indicated in the following:

Construction 5.1. Let (X, \mathcal{B}^X, μ) be a non-empty b-uniform ring space. Then, we put $X^* := X \cup \{\infty\}$ with $\infty \notin X$. For $\mathcal{U} \in \mu$ we are setting:

$$\mathcal{U}^* := \{R^* \subset X^* \times X^* : \exists R \in \mathcal{U} \ R^* \supset R \cup \{(\infty, x) : x \in X^*\}\} \text{ and}$$

$\mathcal{B}^{X^*} := \mathcal{B}^X \cup \{\{\infty\}\}$. Then, $(\mathcal{B}^{X^*}, \underline{b}^*)$ forms a base for a b-uniform ring structure $(\mathcal{B}^{X^*}, \mu^*)$ on X^* , where $\underline{b}^* := \{\mathcal{U}^* : \mathcal{U} \in \mu\}$, compare with 4.7.

Proof. Evidently \mathcal{B}^{X^*} defines a B-set on X^* . Also note that $\mathcal{U}^* \in \text{FIL}(X^* \times X^*)$ holds. As next we infer that for $\mathcal{U} \in \mu$

- {i} $(R \cup \{(\infty, x) : x \in X^*\})(\{\infty\}) = X^*$ for each $R \in \mathcal{U}$ and
- {ii} $(R \cup \{(\infty, x) : x \in X^*\})(B) = R(B)$ for every $R \in \mathcal{U}$ and each $B \in \mathcal{B}^X \setminus \{\emptyset\}$ are valid.

$(X^*, \mathcal{B}^{X^*}, \mu^*)$ is ultracomplete, because the following holds:

Let \mathcal{C}^* be a pre-Chy filter in $(\mathcal{B}^{X^*}, \mu^*)$. We will show that the statement $\mathcal{C}^* q_{\mu^*} \{\infty\}$ can be deduced, meaning that $\overset{\bullet}{\infty} \times \mathcal{C}^* \in \mu^*$ is true. Therefore, it suffices to verify that the inclusion $\overset{\bullet}{\infty} \times \mathcal{C}^* \supset \mathcal{U}^*$ holds for some $\mathcal{U}^* \in \underline{b}^*$.

By the hypothesis and according to 4.7 we can find $\mathcal{V}^* \in \underline{b}^*$ with the corresponding property. Since \underline{b}^* is a ring base we can find $\mathcal{U}^* \in \underline{b}^*$ with $\mathcal{U}^* \subset \mathcal{V}^* \circ \mathcal{V}^*$. Our goal is to verify that $\mathcal{U}^* \subset \overset{\bullet}{\infty} \times \mathcal{C}^*$ holds.

$R^* \in \mathcal{U}^*$ implies $R^* \supset V^* \circ V^*$ for some $V^* \in \mathcal{V}^*$, where $V^* \supset V \cup \{(\infty, x) : x \in X^*\}$ for some $V \in \mathcal{V}$. By applying the corresponding property for \mathcal{C}^* we can find $D \in \mathcal{B}^{X^*}$ with $V^*(D) \in \mathcal{C}^*$. We claim that $\{\infty\} \times V^*(D) \subset V^* \circ V^*$ is true. But $(y, z) \in \{\infty\} \times V^*(D)$ implies the existence of $x' \in D$ such that $(x', z) \in V^*$ with $y = \infty$.

Since $V \cup \{(\infty, x) : x \in X^*\} \subset R^*$ we obtain $(y, x') \in V^*$. Thus $(y, z) \in V^* \circ V^* \subset R^*$ follows, concluding the proof.

Next we infer that the inclusion map $i : (X, \mathcal{B}^X, \mu) \longrightarrow (X^*, \mathcal{B}^{X^*}, \mu^*)$ is b-uniformly continuous, and (X, \mathcal{B}^X, μ) is b-uniform ring subspace of $(X^*, \mathcal{B}^{X^*}, \mu^*)$, compare with 4.10. But this can be done in a straightforward manner. Finally, we have to verify that X is dense in X^* , which means that the equation $cl^{\mu^*}(X) = X^*$ can be deduced, compare with 3.6. So let $z \in X^*$ and without restriction $z = \infty$.

Choose $\mathcal{U} \in \mu$, hence $\mathcal{U}^* \in \underline{b}^*$ follows. It remains to verify that $\{z\} \times X \in sec \mathcal{U}^*$ holds. For $R^* \in \mathcal{U}^*$ we can find $R \in \mathcal{U}$ s.t. $R^* \supset \{(\infty, x) : x \in X^*\} \cup R$. By choosing $x \in X$ we obtain $(z, x) \in \{z\} \times (X \cap R^*)$, and the claim immediately follows. \square

Definition 5.2. Let (X, \mathcal{B}^X, μ) be a non-empty b-uniform ring space and $(X^*, \mathcal{B}^{X^*}, \mu^*)$ the ultracomplete b-uniform ring space as constructed in 5.1, then the pair $(i, (X^*, \mathcal{B}^{X^*}, \mu^*))$ is called the *ultracompletion* of (X, \mathcal{B}^X, μ) (sometimes only the space $(X^*, \mathcal{B}^{X^*}, \mu^*)$ will be called as above stated).

Separation properties come into play if one is considering convergence in a more suitable sense. This is also of importance if universal properties are examined. In the next we are giving some fundamental definitions in this direction.

Definition 5.3. A set-convergence (\mathcal{B}^X, q) is called

- (i) T_0 set-convergence, and the triple (X, \mathcal{B}^X, q) T_0 set-convergence space iff it satisfies the following condition, i.e.
 - (T₀) $B_1, B_2 \in \mathcal{B}^X \setminus \{\emptyset\}$, $\overset{\bullet}{B}_1 q B_2$ and $\overset{\bullet}{B}_2 q B_1$ imply $B_1 = B_2$;
- (ii) T_1 set-convergence, and the triple (X, \mathcal{B}^X, q) T_1 set-convergence space iff it satisfies the following condition, i.e.
 - (T₁) $B_1, B_2 \in \mathcal{B}^X \setminus \{\emptyset\}$ and $\overset{\bullet}{B}_1 q B_2$ imply $B_1 = B_2$;
- (iii) T_2 set-convergence, and the triple (X, \mathcal{B}^X, q) T_2 set-convergence space iff it satisfies the following condition, i.e.
 - (T₂) $\mathcal{F} \in FIL(X)$, $B_1, B_2 \in \mathcal{B}^X \setminus \{\emptyset\}$ with $\mathcal{F} q B_1$ and $\mathcal{F} q B_2$ imply $B_1 = B_2$.

Consequently, we call a b-uniform filter space (X, \mathcal{B}^X, μ) T_0 space (T_1 space, T_2 space, respectively) iff $(X, \mathcal{B}^X, q_\mu)$ is a T_0 set-convergence space (T_1 set-convergence space, T_2 set-convergence space, respectively). Then, related to the latter constructs we also speak of a T_0 ring space (T_1 ring space, T_2 ring space, respectively), and these should be also done when considering b-uniform net spaces.

Remark 5.4. Now, it can be easily seen that T_2 implies T_1 and T_1 implies T_0 . On the other hand we point out that in the discrete case these definitions coincide with those occurring in the theory of point-convergence spaces in the sense of Preuss [22].

Lemma 5.5. For a reordered set-convergence space (X, \mathcal{B}^X, q) each successive pair of conditions are equivalent:

- {i} (\mathcal{B}^X, q) is T_0 set-convergence;
- {ii} $x, z \in X$, $\overset{\bullet}{x} q \{z\}$ and $\overset{\bullet}{z} q \{x\}$ imply $x = z$;
- {iii} (\mathcal{B}^X, q) is T_1 set-convergence;
- {iv} $x, z \in X$ and $\overset{\bullet}{x} q \{z\}$ imply $x = z$;

$\{v\}$ (\mathcal{B}^X, q) is T_2 set-convergence;
 $\{vi\}$ $\mathcal{F} \in FIL(X)$, $x, z \in X$ and $\mathcal{F} q \{x\}$, $\mathcal{F} q \{z\}$ imply $x = z$.

Proof. Evident. □

Proposition 5.6. For a T_0 ring space (X, \mathcal{B}^X, μ) the completion $(X^*, \mathcal{B}^{X^*}, \mu^*)$ is an T_0 ring space.

Proof. Straightforward. □

Remark 5.7. At this point we note that $(X^*, \mathcal{B}^*, \mu^*)$ is never T_1 space, and thus it is also not T_2 space. Now, the following question naturally arises. Does a T_2 ring space or T_1 ring space have an T_2 ultracompletion or T_1 ultracompletion, respectively? But this problem is not the aim of our present paper.

Proposition 5.8. Let (X, \mathcal{B}^X, μ) be a non-empty generated b-uniform ring space and $(X^*, \mathcal{B}^*, \mu^*)$ its ultracompletion. Then, the ultracompletion is generated, too.

Proof. Note that the following inclusion $(\cap\mu)^* \subset \cap\mu^*$ holds. □

Remark 5.9. Taking 4.8 into account we point out that in the discrete case the associated quasi-uniform space of the ultracompletion is up to isomorphism the one- point completion of a given quasi-uniform space in the sense of Carlson and Hicks [3], and thus it is even strongly complete in their terminology. In this context we mention that for a discrete b-uniform filter space (X, \mathcal{B}^X, μ) and for every $\mathcal{F} \in FIL(X)$ the following statements are equivalent:

- (i) \mathcal{F} is pre-Chy filter in (\mathcal{B}^X, μ) ;
- (ii) $\exists \mathcal{U} \in \mu \forall R \in \mathcal{U} \exists x \in X$ with $R(\{x\}) \in \mathcal{F}$.

By taking 5.8 into account, $\mathcal{F} \in FIL(X)$ is pre-Chy filter in a generated b-uniform filter structure (\mathcal{B}^X, μ) iff $\forall R \in \cap\mu$, $\exists B \in \mathcal{B}^X \setminus \{\emptyset\}$ s.t. $R(B) \in \mathcal{F}$.

Thus if combining both statements in the discrete case we obtain the usual classical property of a filter for being Cauchy.

Theorem 5.10. For a generated final b-uniform filter space (X, \mathcal{B}^X, μ) the following statements are, equivalent:

- (i) (X, \mathcal{B}^X, μ) is ultrabounded;
- (ii) $\forall R \in \cap\mu \exists B \subset X$ finite $R(B) = X$.

Proof. to (ii) \Rightarrow (i): Let $\mathcal{F} \in FIL(X) \setminus \{\underline{P}X\}$ be an ultrafilter and $R \in \cap\mu$. Then, we can find points $x_1, \dots, x_n \in X$ such that $X = R(x_1) \cup \dots \cup R(x_n)$ by applying the hypothesis.

But \mathcal{F} is ultrafilter, and thus $R(x_i) \in \mathcal{F}$ for some x_i . Consequently, \mathcal{F} is pre-Chy filter in (\mathcal{B}^X, μ) .

to (i) \Rightarrow (ii): If (i) is not true, then we can find a relation $R \in \cap\mu$ such that $R(B) \neq X$ for all $B \subset X$ finite.

The set $\{X \setminus R(B) : B \subset X \text{ finite}\}$ forms a base for a filter $\mathcal{F} \in FIL(X) \setminus \{\underline{P}X\}$. Let \mathcal{C} be an ultrafilter containing \mathcal{F} . Then, by the hypothesis \mathcal{C} is pre-Chy filter in (\mathcal{B}^X, μ) . Hence we can find $B_1 \in \mathcal{B}^X \setminus \{\emptyset\}$ with $R(B_1) \in \mathcal{C}$. But this is a contradiction because by the hypothesis B_1 is finite, and thus the claim follows. □

Theorem 5.11. *For a non-empty generated final ultrabounded b-uniform ring space (X, \mathcal{B}^X, μ) its ultracompletion $(X^*, \mathcal{B}^{X^*}, \mu^*)$ is final ultrabounded, too.*

Proof. By the construction and hypothesis $(X^*, \mathcal{B}^{X^*}, \mu^*)$ is final. In addition we have that $\cap\mu \in \mu$ is valid, hence $(\cap\mu)^* \in \underline{b}^*$ follows. So let $R^* \in (\cap\mu)^*$, then $R^* \supset R \cup \{(\infty, x) : x \in X^*\}$ for some $R \in \cap\mu$. By applying 5.10 we can find $B \subset X$ finite with $R(B) = X$. We put $B^* := B \cup \{\infty\}$, hence $B^* \subset X^*$ is finite. So it remains to verify that the equation $R^*(B^*) = X^*$ holds.

Let $z \in X^*$, in the case of $z \in X$, we can choose $x \in B$ with $(x, z) \in R$. Consequently, $x \in B^*$ and $(x, z) \in R^*$ follow, showing that $z \in R^*(B^*)$ is true. In the other case, $z = \infty$ implies $z \in B^*$, and $(z, z) \in R^*$ follows, showing the claim, too. \square

Theorem 5.12. *For a non-empty generated final ultrabounded b-uniform ring space (X, \mathcal{B}^X, μ) the b-uniform ring space $(X^*, \mathcal{B}^{X^*}, \mu^*)$ is ultracompact.*

Proof. By applying 2.9 and the former obtained results. \square

Remark 5.13. The outcome just obtained may be of importance, if one intends to consider generalized proximities defined in terms of final ultrabounded b-uniform ring structures. But this line of vision may be left to the reader.

Applied Resume 5.14. At the end of this section we still mention the facts that each non-empty b-uniform net space as well as every non-empty merotopically b-uniform filter space has an ultracompletion, too [17]. Consequently, as a corollary we obtain the result that each quasiuniform limit space has an ultracompletion if supposing the discrete case. Secondly, we can state, that a non-empty merotopically b-uniform filter space possesses at least two different completions, namely the one mentioned above and, in addition, the Cauchy-completion, dealt with in [17].

6. SOME IMPORTANT LINKS TO GENERALIZED APPROACH SPACES

The central idea in approach spaces in the sense of Lowen is that of a distance d , which is a function on $X \times 2^X$ to $[0, \infty]$. Here of fundamental interest is the fact that a distance can be defined not only in a metric space, but also in a topological space, a uniform space and so on. This setting is in fact well motivated by Lowens original axioms for an approach space in terms of its point-set function $d : X \times 2^X \rightarrow [0, \infty]$ listed in [18, 21]. Now, we get some interesting links to our former presented concepts of b-uniform filter spaces, set-convergence spaces, b-topological spaces, see 6.4 or bornological spaces, respectively, see also [10].

First we will give the definition of a so-called approach-bornology on a set X .

Definition 6.1. For a set X a pair (\mathcal{B}^X, d) consisting of non-empty subset $\mathcal{B}^X \subset \underline{P}X$ and a distance function $d : X \times \mathcal{B}^X \rightarrow [0, \infty]$ is called an *approach-bornology*, shortly *apbornology* and the triple (X, \mathcal{B}^X, d) *approach-bornological space* (shortly *apbornological space* or *apb space*, respectively), provided that the following conditions are satisfied,

- (apb₁) $B_1 \subset B \in \mathcal{B}^X$ imply $B_1 \in \mathcal{B}^X$;
- (apb₂) $x \in X$ implies $\{x\} \in \mathcal{B}^X$;

- (apb₃) $B_1, B_2 \in \mathcal{B}^X$ imply $B_1 \cup B_2 \in \mathcal{B}^X$;
- (apb₄) $x \in X$ implies $d(x, \emptyset) = \infty$;
- (apb₅) $x \in X$ implies $d(x, \{x\}) = 0$;
- (apb₆) $x \in X$ and $B_1, B_2 \in \mathcal{B}^X$ imply $d(x, B_1 \cup B_2) = \min\{d(x, B_1), d(x, B_2)\}$.

If $(X, \mathcal{B}^X, d_X), (Y, \mathcal{B}^Y, d_Y)$ are apb spaces then a function $f : X \rightarrow Y$ is called *b-contracted* map provided it satisfies following conditions,

- (bct₁) f is bounded;
- (bct₂) for each $x \in X$ and for each $B \in \mathcal{B}^X$ the inequality $d_Y(f(x), f[B]) \leq d_X(x, B)$ holds.

By **APB** we are denoting the category of apb spaces and b-contracted maps.

Remark 6.2. Here, we point out that \mathcal{B}^X defines a bornology on X in the sense of Hogbe–Nlend [9]. In addition we note that the operator $cl_d : \mathcal{B}^X \rightarrow \underline{P}X$ defined by setting $cl_d(B) := \{x \in X : d(x, B) = 0\}$ forms a b-closure operator on \mathcal{B}^X provided that $cl_d(B) \in \mathcal{B}^X$ is valid for every $B \in \mathcal{B}^X$ [14].

In this context we can specify the term b-contracted by adding that f is also rebounded, if necessary, which means for each $D \in \mathcal{B}^Y$, $f^{-1}[D] \in \mathcal{B}^X$ is valid. We also point out that in the case of $\mathcal{B}^X = \underline{P}X$, the corresponding space is called pre-approach space by F. Mynard and E. Pearl in their book *Beyond Topology* [20]. Here one can find additional propositions concerning this construct.

Furthermore, motivated by Lowen’s idea to define a distance in a topological space we will generalize this concept to a b-closure operator (b-closure) as indicated in the following:

Definition 6.3. In accordance with Leseberg [14], we call a pair (\mathcal{B}^X, h) , where \mathcal{B}^X is bornology and $h : \mathcal{B}^X \rightarrow \underline{P}X$ a function, called *b-closure operator*, a *b-closure structure* (on \mathcal{B}^X) and the triple (X, \mathcal{B}^X, h) *b-closure space*, provided that the following conditions are satisfied:

- (bclo₁) $B \in \mathcal{B}^X$ implies $h(B) \in \mathcal{B}^X$;
- (bclo₂) $h(\emptyset) = \emptyset$;
- (bclo₃) $x \in X$ implies $x \in h(\{x\})$;
- (bclo₄) $B_1 \subset B \in \mathcal{B}^X$ imply $h(B_1) \subset h(B)$;
- (bclo₅) $B_1, B_2 \in \mathcal{B}^X$ imply $h(B_1 \cup B_2) \subset h(B_1) \cup h(B_2)$.

If $(X, \mathcal{B}^X, h^X), (Y, \mathcal{B}^Y, h^Y)$ are b-closure spaces, then a function $f : X \rightarrow Y$ is called *b-continuous map* provided f satisfies the following conditions:

- (bc₁) f is bounded;
- (bc₂) f is rebounded;
- (bc₃) $B \in \mathcal{B}^X$ implies $f[h^X(B)] \subset h^Y(f[B])$.

By **b-CLO** we are denoting the category of b-closure spaces and b-continuous maps.

Remark 6.4. As an important supplement we should note that a b-closure structure (\mathcal{B}^X, h) is called *b-topology* and the triple (X, \mathcal{B}^X, h) *b-topological space* provided that, in addition, the following condition holds:

- (btop) $B \in \mathcal{B}^X$ implies $h(h(B)) \subset h(B)$.

Then, h is called *b-topological operator*. By **b-TOP** we denote the full subcategory of **b-CLO** whose objects are the b-topological spaces [14].

Now, we will give an intrinsic example for the former introduced concept as follows:

Example 6.5. Let a bornological space (X, \mathcal{B}^X) be given and $x \in X$ be a point of X . Then, we define a b-topological operator $t^x : \mathcal{B}^X \rightarrow \underline{P}X$ with fix-point x by setting:

$$\begin{aligned} t^x(\emptyset) &:= \emptyset & \text{and} \\ t^x(B) &:= \{x\} \cup B \quad \text{for } B \in \mathcal{B}^X \setminus \{\emptyset\}. \end{aligned}$$

Remark 6.6. With the now introduced concept it is possible to consider topologies not only on the power set $\underline{P}X$ of X , but also on subsets such as the set of all finite sets, compact sets or totally bounded sets, respectively. In the case of \mathcal{B}^X being saturated, meaning that $X \in \mathcal{B}^X$ holds, b-topological spaces and topological spaces are essentially the same (up to isomorphism). On the other hand classical closure spaces are extensively examined in the book of Čech, so that the concept of b-closure operators also makes sense.

Proposition 6.7. *In a b-closure space (X, \mathcal{B}^X, h) we set $\delta_h(x, B) := 0$ iff $x \in h(B)$ and $\delta_h(x, B) := \infty$, otherwise. Then, the pair $(\mathcal{B}^X, \delta_h)$ satisfies the conditions for an apbornology, and it is compatible with the b-closure operator h .*

Proof. Evidently, cl_{δ_h} defines a b-closure operator, see also 6.2, and the following sequence of equivalences is valid, i.e. $x \in cl_{\delta_h}(B) \Leftrightarrow \delta_h(x, B) = 0 \Leftrightarrow x \in h(B)$. \square

Remark 6.8. As seen above to make sure that in general $cl_d : \mathcal{B}^X \rightarrow \underline{P}X$ forms a b-closure operator it is necessary to provide the condition in 6.2. Now the question arises, whether the associated b-closure (\mathcal{B}^X, cl_d) is compatible with the given apbornology (\mathcal{B}^X, d) . To this end, we are giving the following condition:

Definition 6.9. An apbornology (\mathcal{B}^X, d) is called *covered*, and the triple (X, \mathcal{B}^X, d) *covered apbornological space* (shortly *covered apb space*) provided that the following conditions are satisfied:

- (cov₁) $B \in \mathcal{B}^X$ implies $cl_d(B) \in \mathcal{B}^X$;
- (cov₂) $B \in \mathcal{B}^X$ and $x \notin cl_d(B)$ imply $d(x, B) = \infty$.

By **COV-APB** we denote the subcategory of **APB**, whose objects are covered.

Proposition 6.10. *For a covered apbornological space (X, \mathcal{B}^X, d) the following equation holds, i.e. $\delta_{cl_d} = d$.*

Proof. Let $x \in X$ and $B \in \mathcal{B}^X$. In the case of $x \in cl_d(B)$, we have $d(x, B) = 0$ and $\delta_{cl_d}(x, B) = 0$, which shows the equality. If $x \notin cl_d(B)$, then $d(x, B) = \infty$ by applying (cov₂). But on the other hand $\delta_{cl_d}(x, B) = \infty$ also follows, thus implying the claim. So it remains to verify that δ_h is satisfying (cov₂), because by 6.3 we have $cl_{\delta_h}(B) = h(B) \in \mathcal{B}^X$, thus implying (cov₁). $x \notin cl_{\delta_h}(B)$ implies $x \notin h(B)$, hence $\delta_h(x, B) = \infty$, so that δ_h fulfills (cov₂). \square

Proposition 6.11. *For b-closure spaces $(X, \mathcal{B}^X, h^X), (Y, \mathcal{B}^Y, h^Y)$ let $f : X \rightarrow Y$ be a function, then the following statements are equivalent:*

- (i) $f : (X, \mathcal{B}^X, h^X) \rightarrow (Y, \mathcal{B}^Y, h^Y)$ is b-continuous;
- (ii) $f : (X, \mathcal{B}^X, \delta_{h^X}) \rightarrow (Y, \mathcal{B}^Y, \delta_{h^Y})$ is b-contracted.

Proof. Consider remark 6.2.

to (i) \Rightarrow (ii): So let $x \in X$ and $B \in \mathcal{B}^X$. In the case of $x \in h^X(B)$, $\delta_{h^X}(x, B) = 0$, and by the hypothesis $f(x) \in h^Y(f[B])$ follows, showing that $\delta_{h^Y}(f(x), f[B]) = 0$ is true, and the claim in (ii) results. In the case of $x \notin h^X(B)$, $\delta_{h^X}(x, B) = \infty$ is valid. Since $\delta_{h^Y}(f(x), f[B]) \in [0, \infty]$ holds we obtain $\delta_{h^Y}(f(x), f[B]) \leq \infty = \delta_{h^X}(x, B)$, and the claim follows.

to (ii) \Rightarrow (i): Let $B \in \mathcal{B}^X$ and $y \in f[h^X(B)]$. Our goal is that $\delta_{h^Y}(y, f[B]) = 0$ can be deduced.

We have $y = f(x)$ for some $x \in h^X(B)$, and consequently $\delta_{h^X}(x, B) = 0$ follows. But by the hypothesis f is b-contracted, i.e. $\delta_{h^Y}(f(x), f[B]) \leq \delta_{h^X}(x, B)$ holds, and the claim results. \square

Theorem 6.12. *The categories **COV-APB** and **b-CLO** are isomorphic.*

Proof. Evident, by applying 6.4, 6.5, 6.6, 6.7, 6.8, 6.9 and 6.10, respectively. \square

To obtain a corresponding embedding of **b-TOP** into **APB** we have to specify the concept of a covered apbornology as follows:

Definition 6.13. A covered apbornology (\mathcal{B}^X, d) is called *topoform*, and the triple (X, \mathcal{B}^X, d) *topoform apb space*, provided that the following condition is satisfied,

(top) $x \in X$ and $B \in \mathcal{B}^X$ imply $d(x, B) \leq d(x, cl_d(B))$.

By **TOP-APB** we denote the full subcategory of **CLO-APB**, whose objects are topoform.

Remark 6.14. It is easy to see that if (\mathcal{B}^X, d) forms a topoform apbornology, then $cl_d : \mathcal{B}^X \rightarrow \underline{PX}$ defines a b-topological operator on \mathcal{B}^X .

Theorem 6.15. *The categories **TOP-APB** and **b-TOP** are isomorphic.*

Proof. By applying the results obtained earlier and taking into account the following last reflection, i.e. for a b-topological operator $t : \mathcal{B}^X \rightarrow \underline{PX}$, $x \in X$ and $B \in \mathcal{B}^X$ we consider the two distances, i.e. $\delta_t(x, B)$ and $\delta_t(x, cl_{\delta_t}(B))$, respectively. In the case of $x \in t(B)$, $\delta_t(x, B) = 0$. On the other hand we get $x \in t(t(B))$, hence $\delta_t(x, t(B)) = 0$ implying $x \in cl_{\delta_t}(t(B)) = cl_{\delta_t}(B)$, thus $\delta_t(x, cl_{\delta_t}(B)) = 0$, and the claim follows. If secondly $x \notin t(B)$, then $\delta_t(x, B) = \infty$ is valid. On the other hand we have $x \notin t(t(B))$, since t satisfies (btop). Consequently, $\infty = \delta_t(x, t(B)) = \delta_t(x, cl_{\delta_t}(B))$ follows, showing the claim too. \square

Remark 6.16. Our last result now makes sure that the category **APB** and the category of generalized near spaces, denoted by **SD** [17] have a non-empty intersection, which contains **b-TOP**.

Next we will give a slight modification for the conditions of being an apbornology.

Definition 6.17. For a bornology \mathcal{B}^X let $d : X \times \mathcal{B}^X \rightarrow [0, \infty]$ be a function so that (\mathcal{B}^X, d) satisfies the following conditions, i.e.

(pre-apb₁) $x \in X$ implies $d(x, \emptyset) = \infty$;

(pre-apb₂) $x \in B \in \mathcal{B}^X$ imply $d(x, B) = 0$.

Then, (\mathcal{B}^X, d) is called a *pre-apbornology* (on X) and the triple (X, \mathcal{B}^X, d) *pre-apbornological space* (shortly *pre-apb space*). By **PRE-APB** we denote the category, whose objects are the pre-apb spaces and whose morphisms between them satisfy the conditions in 6.1.

Remark 6.18. Evidently, every apbornological space is a pre-apb space.

Now, let us return to the concept of pointset- convergence spaces, compare also with [19].

Proposition 6.19. *For a pointset- convergence space (X, \mathcal{B}^X, q) (see also 3.2), we put:*

$$\begin{aligned} d_q(x, B) &= 0 && \text{iff } \overset{\bullet}{x} \ q \ B \ \text{and} \\ d_q(x, B) &= \infty && \text{otherwise.} \end{aligned}$$

Then, (\mathcal{B}^X, d_q) forms a *pre-apbornology*.

Proof. to (pre-apb₁) $d_q(x, \emptyset) = \infty$ holds, since $\overset{\bullet}{x}$ is not in relation with \emptyset . Otherwise $\overset{\bullet}{x} = \underline{P}X$ is a contradiction.

to (pre-apb₂) For $x \in B \in \mathcal{B}^X$ $\overset{\bullet}{B} \ q \ B$ and $\overset{\bullet}{B} \subset \overset{\bullet}{x}$ are valid, implying $\overset{\bullet}{x} \ q \ B$, hence $d_q(x, B) = 0$ follows.

Conversely, for a pre-apbornology (\mathcal{B}^X, δ) we are setting:

$$\begin{aligned} \mathcal{F} \ p_\delta \ \emptyset & \text{ iff } \mathcal{F} = \underline{P}X \ \text{and} \\ \mathcal{F} \ p_\delta \ B & \text{ iff } \forall x \in B \ \exists F \in \mathcal{F} \cap \mathcal{B}^X \ \delta(x, F) = 0 \ \text{for } B \in \mathcal{B}^X \setminus \{\emptyset\}. \end{aligned}$$

Then, obviously $(\mathcal{B}^X, p_\delta)$ defines a pointset-convergence. □

In this context we mention that convergence on approach spaces is extensively studied by Lowen or Brock [2,19], respectively under name of convergence approach spaces. So it was shown that the axiom (F) defined for limit spaces by Cook and Fischer can be extended to an axiom (F) for convergence approach spaces so that the full subcategory of **CAP** (convergence approach spaces), whose objects satisfy (F) is isomorphic to the category **AP** of approach spaces.

Now, the question arises, whether (\mathcal{B}^X, d_q) is compatible with the pointset-convergence (\mathcal{B}^X, q) , meaning that $p_{\delta_q} = q$ can be deduced. But this seems only to be possible by adding suitable properties for the given pointset-convergence as done in the following:

Definition 6.20. A pointset-convergence (\mathcal{B}^X, q) is called *rotary* and the triple (X, \mathcal{B}^X, q) *rotary pointset-convergence space*, provided that the following conditions are satisfied, i.e. For $\mathcal{F} \in \text{FIL}(X)$ and each $x \in X$ let being valid:

- (rot₁) $F \in \mathcal{F} \cap \mathcal{B}^X$ and $\overset{\bullet}{x} \ q \ F$ imply $\mathcal{F} \ q \ \{x\}$;
- (rot₂) $\mathcal{F} \ q \ \{x\}$ implies $\exists F \in \mathcal{F} \cap \mathcal{B}^X$ s.t. $\overset{\bullet}{x} \ q \ F$.

By **RP-SETCONV** we denote the full subcategory of **P-SETCONV**, whose objects are rotary.

Proposition 6.21. *Let a rotary pointset- convergence space (X, \mathcal{B}^X, q) be given, then the pre-apbornology (\mathcal{B}^X, d_q) as defined in 6.19 is compatible.*

Proof. So let without restriction $B \in \mathcal{B}^X \setminus \{\emptyset\}$ and at first $\mathcal{F} p_{d_q} B$. Then, for each $x \in B$ we can find $F \in \mathcal{F} \cap \mathcal{B}^X$ such that $d_q(x, F) = 0$ is valid. Hence $\dot{x} q F$ follows, and $\mathcal{F} q \{x\}$ results by applying (rot_1) . Consequently, we obtain $\mathcal{F} q B$, since by the hypothesis (\mathcal{B}^X, q) is a pointset-convergence.

Conversely, for $\mathcal{F} q B$ let $x \in B$. Since (\mathcal{B}^X, q) is reordered $\mathcal{F} q \{x\}$ follows implying the existence of $F \in \mathcal{F} \cap \mathcal{B}^X$ with $\dot{x} q F$ by applying (rot_2) , hence $d_q(x, F) = 0$, and $\mathcal{F} p_{d_q} B$ results. \square

To ensure that the pointset-convergence $(\mathcal{B}^X, p_\delta)$ is rotary the pre-apbornology (\mathcal{B}^X, δ) has to be reflexive in the following sense:

Definition 6.22. A pre-apbornology (\mathcal{B}^X, d) is called *reflexive* and the triple (X, \mathcal{B}^X, d) an *reflexive pre-apb space* provided that the following condition holds:

(ref) $z \in X, F \in \mathcal{B}^X$ and $d(z, F) = 0$ imply $x = z$ for every $x \in F$.

By **RPRE-APB** we denote the full subcategory of **PRE-APB**, whose objects are reflexive.

Remark 6.23. For a pre-apbornology (\mathcal{B}^X, d) let d be injective, then (\mathcal{B}^X, d) is reflexive. On the other hand for a reflexive apbornology (\mathcal{B}^X, d) the bounded sets of \mathcal{B}^X are closed meaning that $cl_d(B) = B$ holds for every $B \in \mathcal{B}^X$.

Proposition 6.24. For a reflexive pre-apbornology (\mathcal{B}^X, δ) the pointset-convergence $(\mathcal{B}^X, p_\delta)$ is a rotary T_1 set-convergence.

Proof. to (rot_1) : For $\mathcal{F} \in \text{FIL}(X), x \in X$ and $F \in \mathcal{F} \cap \mathcal{B}^X$ let $\dot{x} p_\delta F$. Choose $z \in F$, hence by the hypothesis we can find $F_1 \in \dot{x} \cap \mathcal{B}^X$ with $\delta(x, F_1) = 0$. But $x \in F_1$ implies $z = x$, because (\mathcal{B}^X, d) is reflexive. Consequently, $x \in F$ follows, and according to (pre-apb_2) $\delta(x, F) = 0$ results implying $\mathcal{F} p_\delta \{x\}$.

to (rot_2) : $\mathcal{F} p_\delta \{x\}$ implies the existence of $F \in \mathcal{F} \cap \mathcal{B}^X$ with $\delta(x, F) = 0$. Let $z \in F$, hence $x = z$ by the hypothesis, and $x \in F$ follows, showing that $F \in \dot{x}$ is true. But $(\mathcal{B}^X, p_\delta)$ is a pointset-convergence, and the claim results.

to (T_1) : For $x, z \in X$ let $\dot{x} p_\delta \{z\}$, hence we can find $F \in \dot{x} \cap \mathcal{B}^X$ with $\delta(z, F) = 0$ implying $x \in F$, and by the hypothesis $x = z$ follows (compare also with 5.5). \square

Proposition 6.25. For a T_1 pointset-convergence $(\mathcal{B}^X, q), (\mathcal{B}^X, d_q)$ is reflexive.

Proof. $z \in X, F \in \mathcal{B}^X$ and $d_q(x, F) = 0$ imply $\dot{x} q F$ by the definition. Let $x \in F$, then we get $\dot{x} q \{z\}$ according to (RO), and $x = z$ follows, since (\mathcal{B}^X, q) is T_1 set-convergence. \square

Definition 6.26. A reflexive pre-apbornology (\mathcal{B}^X, δ) is called *convergent*, and the triple $(X, \mathcal{B}^X, \delta)$ *convergent pre-apb space*, provided that the following condition is satisfied:

(conv) $x \in X, B \in \mathcal{B}^X$ and \dot{x} is not in relation under p_δ with B imply $\delta(x, B) = \infty$.

By **CPRE-APB** we denote the full subcategory of **RPRE-APB**, whose objects are convergent.

Proposition 6.27. *For a convergent pre-apbornology (\mathcal{B}^X, δ) the equation*

$$d_{p_\delta} = \delta$$

holds.

Proof. Let $x \in X$ and $B \in \mathcal{B}^X$. In the first case of $\dot{x} p_\delta B$, we have $d_{p_\delta}(x, B) = 0$. On the other hand choose $z \in B$, hence $\delta(z, B) = 0$. Moreover by the definition of p_δ we can find $F \in \dot{x} \cap \mathcal{B}^X$ with $\delta(z, F) = 0$. But $x \in F$ implies $x = z$, since (\mathcal{B}^X, δ) is reflexive, and $\delta(x, B) = 0$ follows which shows the claim. Secondly, if \dot{x} is not in relation under p_δ with B then $d_{p_\delta}(x, B) = \infty = \delta(x, B)$ are true by applying the hypothesis. \square

Now if we denote by **T₁RP-SETCONV** the full subcategory of

RP-SETCONV

whose objects are T_1 set- convergence spaces we obtain the following result:

Theorem 6.28. *The categories **T₁RP-SETCONV** and **CPRE-APB** are isomorphic.*

Proof. Evident, by taking into account the last verified equations. So it only remains to prove the following equivalence of statements, i.e., for convergent pre-apb spaces $(X, \mathcal{B}^X, d^X), (Y, \mathcal{B}^Y, d^Y)$ let $f : X \rightarrow Y$ be a map. Then, following statements are equivalent,

- (i) $f : (X, \mathcal{B}^X, d^X) \rightarrow (Y, \mathcal{B}^Y, d^Y)$ is b-contracted;
- (ii) $f : (X, \mathcal{B}^X, p_{d^X}) \rightarrow (Y, \mathcal{B}^Y, p_{d^Y})$ is b-continuous.

to (i) \Rightarrow (ii): Let $\mathcal{F} p_{d^X} B$ and $y \in f[B]$, hence $y = f(x)$ for some $x \in B$. By the hypothesis there exists $F \in \mathcal{F} \cap \mathcal{B}^X$ with $d_X(x, F) = 0$. Since f is b-contracted $d^Y(f(x), f[F]) \leq d^X(x, F) = 0$ and $f[F] \in f(\mathcal{F}) \cap \mathcal{B}^Y$ follow, implying $d^Y(y, f[F]) = 0$, and the claim results.

to (ii) \Rightarrow (i): For $x \in X$ and $B \in \mathcal{B}^X$ we consider $d^X(x, B)$ as well as

$$d^Y(f(x), f[B]).$$

But $d^X(x, B) = d_{p_{d^X}}(x, B)$ and $d^Y(f(x), f[B]) = d_{p_{d^Y}}(f(x), f[B])$.

In the case of $\dot{x} p_{d^X} B$, we have $d^X(x, B) = d_{p_{d^X}}(x, B) = 0$ and $f(x) p_{d^Y} f[B]$. But $d_Y(f(x), f[B]) = d_{p_{d^Y}}(f(x), f[B]) = 0$ implies $d^Y(f(x), f[B]) \leq d^X(x, B)$. Secondly if \dot{x} is not in relation under p_{d^X} with B we get $d^X(x, B) = d_{p_{d^X}}(x, B) = \infty$ with $d^Y(f(x), f[B]) \leq \infty$, and the claim follows. \square

Our next definition provides a closed connection between bornological spaces and apbornological spaces in the sense that **BORN** can be regarded as a full embedded subcategory of **APB**. Hence in view of 1 and 4.5, respectively **b-URING** and **APB** intersects.

Definition 6.29. An apbornology (\mathcal{B}, δ) is called *elementary*, and the triple $(X, \mathcal{B}^X, \delta)$ an *elementary apbornological space* provided that the following condition is satisfied,

- (e) $x \notin B$ implies $\delta(x, B) = \infty$.

By **E-APB** we denote the full subcategory of **APB**, whose objects are elementary.

Theorem 6.30. *The categories **E-APB** and **BORN** are isomorphic.*

Proof. For a bornological space (X, \mathcal{B}^X) we define a distance function $d_b^X : X \times \mathcal{B}^X \rightarrow [0, \infty]$ by setting for each pair $(x, B) \in X \times \mathcal{B}^X$:

$$\begin{aligned} d_b^X(x, B) &:= 0 && \text{iff } x \in B; \\ d_b^X(x, B) &:= \infty, && \text{otherwise.} \end{aligned}$$

Then, the natural corresponding assignments are functorial and determine the announced isomorphism between the two categories in question. \square

Remark 6.31. By applying 2.7 we can state that every non-empty elementary apbornological space is ultracomplete, up to isomorphism.

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